Offline Evaluation of Ranking Policies with Click Models

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Motivation

Amazon, Facebook, Netflix
Motivation

Production Policy $\pi$

Number of clicks: $V(\pi) = 1$

Hypothetical Policy $h$

Number of clicks: $V(h) = 2$

• How can we know $V(h) = 2$?

Search “London” @ Adobe Stock
Directly Implementing New Policy $h$

Risks for directly implementing new policy $h$

- Expensive
- Uses a portion of live users and poor policy might harm user experience
- Not replicable

Can we know $V(h) = 2$ without directly implementing it?

Offline Evaluation!
• Lists: $A = (a_1, \ldots, a_K)$

• The value of list $A$ with the click realization $w$:

$$V(A; w) = \sum_{k=1}^{K} w(a_k, k)$$

• The value of a policy $h$:

$$V(h) = \mathbb{E}_{x, w, A \sim h(\cdot | x)} [V(A; w)]$$
• Suppose the clicks depend only on (item, position) pairs
• The CTR of putting item $a$ at $k$-th position under context $x$ is

\[ \bar{w}(a, k | x) \]

• The expected value of $A$

\[ V(A) = \sum_{k=1}^{K} \bar{w}(a_k, k | x) \]
Logged dataset $S = \{(x_t, A_t, W_t)\}_{t=1}^n$

- At each time $t$
  - The environment draws context $x_t$ and click realizations $w_t$
  - The learner observes $x_t$ and selects $A_t$ according to policy $\pi$
  - The environment reveals $\{w_t(a_t^k, k)\}_{k=1}^K$

Objective

- To design statistically efficient estimators based on logged dataset for any ranking policy

Challenge

- The number of different lists is exponential in $K$
• Direct Method

\[ \hat{V}(h) = \frac{1}{n} \sum_{t=1}^{n} \sum_{a} \sum_{k=1}^{K} h(a, k | x_t) \hat{w}(a, k | x_t) \]

• Can be used to evaluate any policy
• Unstable when the number of observations for some item is small
• No theoretical guarantee for known computationally efficient method for some click models
Existing Method - Unstructured List Estimator [Strehl et al. 2010]

• Importance sampling (for list level)

\[
V(h) = \mathbb{E}_{A \sim h}[V(A)]
\]

\[
= \mathbb{E}_{A \sim h} \left[ V(A) \cdot \frac{\pi(A)}{\pi(A)} \right]
\]

\[
= \mathbb{E}_{A \sim \pi} \left[ V(A) \cdot \frac{h(A)}{\pi(A)} \right]
\]

• List estimator

\[
\hat{V}_L(h) = \frac{1}{|S|} \sum_{(x,A,w) \in S} V(A; w) \min \left\{ \frac{h(A | x)}{\hat{\pi}(A | x)}, M \right\}
\]

Trade-off between bias and variance

Empirical distribution over logged data
List Estimator - Disadvantages

- Disadvantages
  - Have to match the exact lists
  - The number of lists is exponential in $K$, thus $\hat{\pi}(A \mid x)$ is very small

Logged Data

- 3
- 2
- 1
- 4
- 5
- 2
- 1
- 3
- 4

Test List

- 4
- 5
- 2
- 1
- 3
- 2
- X

Click ☐ No Click
\( \tilde{w}(a, k | x) \) only depends on item \( a \), for any context \( x \)
Estimators for DCTR

- DCTR: \( \tilde{w}(a, k \mid x) \) only depends on item \( a \) for any context \( x \)

\[
\hat{V}_I(h) = \frac{1}{|S|} \sum_{(x,A,w) \in S} \sum_{k=1}^{K} \min \left\{ \frac{h(a_{\hat{r}} \mid x)}{\hat{\pi}(a_{\hat{r}} \mid x)}, M \right\}
\]

- List estimator

\[
\hat{V}_L(h) = \frac{1}{|S|} \sum_{(x,A,w) \in S} \sum_{k=1}^{K} \min \left\{ \frac{h(A \mid x)}{\hat{\pi}(A \mid x)}, M \right\}
\]
### Estimators for Click Models

<table>
<thead>
<tr>
<th>Click Model</th>
<th>Assumption</th>
<th>Estimator</th>
</tr>
</thead>
<tbody>
<tr>
<td>Random</td>
<td>$\tilde{w}(a, k \mid \cdot)$ constant</td>
<td>$\hat{V}_R$</td>
</tr>
<tr>
<td>Rank-Based</td>
<td>$\tilde{w}(a, k \mid \cdot)$ only depends on position $k$</td>
<td>$\hat{V}_R$</td>
</tr>
<tr>
<td>Document-Based</td>
<td>$\tilde{w}(a, k \mid \cdot)$ only depends on item $a$</td>
<td>$\hat{V}_I$</td>
</tr>
<tr>
<td>Position-Based</td>
<td>$\tilde{w}(a, k \mid \cdot) = \mu(a \mid \cdot) p(k \mid \cdot)$</td>
<td>$\hat{V}_{\text{PBM}}$</td>
</tr>
<tr>
<td>Item-Position</td>
<td>$\tilde{w}(a, k \mid \cdot)$</td>
<td>$\hat{V}_{\text{IP}}$</td>
</tr>
</tbody>
</table>
Proposition (Unbiased in a larger class of policies)
The structured estimators are unbiased in a larger class of policies than list estimator.

Proposition (Lower bias in estimating policy)
The structured estimators have lower bias than list estimator.

Proposition (Better guarantee for policy optimization)
The best policy found by structured estimators have better theoretical guarantees than that by list estimator.
Experiments

Personalized Web Search Challenge

Yandex

Re-rank web documents using personal preferences
$9,000 · 194 teams · 5 years ago

- Recorded over 27 days
- Each record contains
  - A query ID
  - The day when the query occurs
  - 10 displayed item as a response to the query
  - The corresponding click indicators of each displayed items

- Logged dataset $S$
  - Any record except day $d$
  - $\hat{\pi}$ is the empirical distribution over $S$

- Evaluation policy $h$
  - Records of day $d$
  - $h$ is the empirical distribution over these records
  - $V(h)$ is the average CTR for these records
Experiments - Example Query with $K = 3$

(b) Query 11655238: $K = 3$

- Structured estimators better
- Tuning of $M$ matters
Experiments - 100 Most Frequent Queries with $K = 2$

- IP estimator improves 18% over list estimator
- IP estimator improves 13% over RCTR estimator
Experiments - 100 Most Frequent Queries with $K = 3$

(b) 100 Queries: $K = 3$

- IP estimator improves 46% over list estimator
- IP estimator improves 13% over RCTR estimator
Experiments - 100 Most Frequent Queries with $K = 10$, DCG

- IP estimator improves 82% over list estimator
- IP estimator improves 11% over RCTR estimator
Conclusions

- We propose various estimators for the expected number of clicks on lists generated by ranking policies that leverage the structure of click models
- We prove that our estimators are better than the unstructured list estimators
  - Less biased
  - Better guarantees for policy optimization
- Our estimators consistently outperform the list estimator in experiments
